

UNIVERSITAS NEGERI YOGYAKARTA

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Bachelor of Science in Mathematics

MODULE HANDBOOK

| Module name: | Introduction to Dynamical Systems |
|--|---|
| Module level, if applicable: | Undergraduate |
| Code: | MAT6351 |
| Sub-heading,ifapplicable: | - |
| Classes,ifapplicable: | - |
| Semester: | 6 th |
| Module coordinator: | Kus Prihantoso Krisnawan, M.Si. |
| | 1. Dr. Hartono; |
| Lecturer(s): | 2. Kus Prihantoso K., M.Si. |
| Language: | Bahasa Indonesia |
| Classification within the curriculum: | Objective course |
| Teaching format / class hoursperweekduring the semester: | 150 minutes lectures and 180 minutes structured activities per week. |
| Workload: | Total workload is 136 hours per semester which consists of 150 minutes lectures, 180 minutes structured activities, and 180 minutes self-study per week for 16 weeks. |
| Creditpoints: | 3 |
| Prerequisites course(s): | Differential Equations (MAT6214) |
| Courseoutcomes: | After taking this course the students have ability to: CO 1. Respecting other people's views, opinions,and original ideas |
| | CO 2. Understanding definitions, theorems, some forms of phase portraits, and nature of the solution of dynamical |

| | systems using critical and systematic thinking in a | | | | | | | | |
|--------------------------|---|--|--|--|--|--|--|--|--|
| | manner individually or groups | | | | | | | | |
| | CO 3. Communicating, in writing or verbally, ideas to | | | | | | | | |
| | understand or solve mathematical problems. | | | | | | | | |
| | CO 4. Explaining the meaning of the phase portraits and the | | | | | | | | |
| | nature of solution to figure out the characteristics of dynamical system critical points. | | | | | | | | |
| | | | | | | | | | |
| | CO 5. Making an appropriate dynamical system models and a | | | | | | | | |
| | computer simulation of dynamical system solutions. | | | | | | | | |
| | This course containsdefinitions and theorems as the | | | | | | | | |
| | foundations of mathematics dynamical systems, methods to | | | | | | | | |
| | get solutions of linear systems, and methods to see the nature | | | | | | | | |
| | of solutions. As the foundations, the discussed theories are | | | | | | | | |
| | the definition of dynamical system, diagonalization, eigen | | | | | | | | |
| Content: | values, and eigen vectors. Meanwhile, the methods of getting | | | | | | | | |
| Content. | solutions for linear systems which have real numbers but | | | | | | | | |
| | different eigen values, complex eigen values, and the same | | | | | | | | |
| | eigen values. And finally, the nature of the solutions will be | | | | | | | | |
| | explained by linearization, Lyapunov method, center manifold | | | | | | | | |
| | theorem, normal form, and some methods to see if the | | | | | | | | |
| | solutions have periodic orbits or undergo bifurcations. | | | | | | | | |
| | CO1: Attitude assessment is carried out at each meeting | | | | | | | | |
| | using observation and / or self-assessment techniques by the | | | | | | | | |
| | assumption that every student is good. The student will be | | | | | | | | |
| | given a value as very good or not good if he/she shows, | | | | | | | | |
| | significantly, excellent or poor attitude. The results of attitude | | | | | | | | |
| | assessment used as one of the graduation requirements. | | | | | | | | |
| Study/exam achievements: | | | | | | | | | |
| | The final grades will be weight as follow: | | | | | | | | |
| | NoCOObjek PenilaianTeknikBobotPenilaian | | | | | | | | |
| | 1CO 2, and 4a. PresentationObservation10%b. IndividualWritten10% | | | | | | | | |
| | Assignment | | | | | | | | |
| | c. QuizWritten20%2CO 3 and 5a. GroupWritten10% | | | | | | | | |
| L | | | | | | | | | |

| | | | Aggignment | | | | | |
|-----------------|--|--|---------------|-------|------|--|--|--|
| | | | Assignment | | 2004 | | | |
| | | | b. Mid test | | 20% | | | |
| | | | c. Final test | | 30% | | | |
| | | | | Total | 100% | | | |
| Forms of media: | Board, LCD Projector, Laptop/Computer | | | | | | | |
| | 1. Perko, L. 2000. Differential Equations and Dynamical | | | | | | | |
| | Systems. New York: Springer-Verlag. 2. Kuznetsov, Y.A. 1998. Elements of applie | | | | | | | |
| | | | | | | | | |
| | theory. Second Edition. New York: Springer-Verla 3. Wiggins, S. 1990. Introduction to applied | | | | | | | |
| Literature: | | | | | | | | |
| | dynamical systems and chaos. New York: Springer- | | | | | | | |
| | Verlag. | | | | | | | |
| | 4. Verhulst, F. 1990. Nonlinear differential equations and | | | | | | | |
| | dynamical systems.New York: Springer Science. | | | | | | | |

PLO and CO mapping

| | PLO1 | PLO2 | PLO3 | PLO4 | PLO5 | PLO6 | PLO7 | PLO8 | PLO9 | PLO10 |
|-----|------|------|------|------|------|------|------|------|------|-------|
| CO1 | | ✓ | | | | | | | | |
| CO2 | | | ✓ | | | | | | | |
| CO3 | | | | ✓ | | | | | | |
| CO4 | | | | | ✓ | | | | | |
| CO5 | | | | | | | ✓ | | | |
| CO6 | | | | | | | | | | |